ON THE OPEN SET CONDITION FOR SELF-SIMILAR FRACTALS

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Abstract. For self-similar sets, the existence of a feasible open set is a natural separation condition which expresses geometric as well as measure-theoretic properties. We give a constructive approach by defining a central open set and characterizing those points which do not belong to feasible open sets.

1. Introduction

Self-similar sets. Let $f_1, \ldots, f_m$ be contracting similarity maps on $\mathbb{R}^n$, that is

$$|f_i(x) - f_i(y)| = r_i \cdot |x - y|$$

for all $x, y \in \mathbb{R}^n$. The $r_i \in (0, 1)$ are the contraction factors, $| \cdot |$ denotes the Euclidean norm. There is a unique compact set $A$ which satisfies the set equation

$$A = f_1(A) \cup \ldots \cup f_m(A)$$

and is called the self-similar set generated by the maps $f_i$ [3, 2]. The set $A$ consists of similar copies $A_i = f_i(A)$ of itself, each $A_i$ consists of smaller copies $A_{ij} = f_i(f_j(A))$, and so on. For any integer $n$, we can consider the set $S^n$ of words $i = i_1 \ldots i_n$ from the alphabet $S = \{1, \ldots, m\}$. Writing $f_i = f_{i_1} \cdots f_{i_n}$ and $A_i = f_i(A)$, we can express $A$ as

$$A = \bigcup \{A_i \mid i \in S^n\}.$$

When $n$ tends to infinity, this induces a continuous map $\pi : S^\infty \to A$ from the set $S^\infty$ of sequences $i_1 i_2 i_3 \ldots$ onto the self-similar set, the so-called address map.

The open set condition (OSC). The $f_i$ are said to satisfy the OSC if there exists a nonempty open set $V \subset \mathbb{R}^n$ such that

$$\bigcup_{i=1}^m f_i(V) \subseteq V \quad \text{and} \quad f_i(V) \cap f_j(V) = \emptyset \quad \text{for } i \neq j.$$

We call $V$ a feasible open set of the $f_i$, or of $A$. The OSC controls the overlap of the $A_i$. It was introduced by P.A.P. Moran [5] already 1946 in order to show that the canonical Hausdorff measure is positive on $A$. More recently, Schief [6] proved the converse: positive Hausdorff measure implies OSC. They also proved that OSC is equivalent to a combinatorial condition: there exists an integer $N$ such that at
most $N$ incomparable pieces $A_j$ of size $\geq \varepsilon$ can intersect the $\varepsilon$-neighborhood of a piece $A_i$ of diameter $\varepsilon$.

The neighbor map condition. An algebraic equivalent for OSC was given by Bandt and Graf [1]. The inverse map $f_i^{-1}$ is used to transform the small pieces $f_i(A)$ and $f_j(A)$ into $A$ and $h(A) = f_i^{-1}f_j(A)$ respectively. Here $h(A)$ is “the potential neighbor set” of $A$ if we imagine that the self-similar structure is extended outward $A$. The second requirement of the OSC can be written as $f_i(V) \cap f_j(V) = \emptyset$ for $i_1 \neq j_1$, and this is equivalent to $V \cap f_i^{-1}f_j(V) = \emptyset$. If such an open set $V$ exists, then the map $h = f_i^{-1}f_j$ cannot be near the identity map $id$. Let $S^* = \bigcup_{n \geq 1} S^n$. The maps in

$$N = \{h = f_i^{-1}f_j \mid i, j \in S^*, \ i_1 \neq j_1\}$$

will be called neighbor maps. The algebraic formulation of OSC reads as follows.

There is a constant $\kappa > 0$ such that $\|h - id\| > \kappa$ for all neighbor maps $h$.

The norm of an affine mapping $g$ on $\mathbb{R}^n$ is $\|g\| = \sup_{\|x\| \leq 1} |g(x)|$, as usual. Geometrically, the condition says that compared to their size two pieces $A_i$ and $A_j$ cannot be arbitrarily close to each other.

Figure 1. Some neighbor sets and central open set for the Sierpinski gasket

Figure 2. a) Neighbor sets and central open set for the Koch curve

b) A feasible open set which contains the central one
2. The central open set

So far, no algorithm is known to construct feasible open sets. Here we give a constructive approach. Let us say that \( x \in \mathbb{R}^n \) is a forbidden point for \( A \) if there is no feasible open set \( V \) containing \( x \).

All points of a “neighbor set” \( h(A) = f_i^{-1}f_j(A) \) are forbidden points for \( A \). This will follow from Proposition 3 and can easily be proved directly. Thus an open set \( V \) cannot contain points of the set \( H = \bigcup \{ h(A) \mid h \in \mathcal{N} \} \). So let us define the central open set for \( f_1, \ldots, f_m \) as

\[
V_c = \{ x \mid d(x, A) < d(x, H) \}
\]

where \( d(x, Y) = \inf \{ |x-y| \mid y \in Y \} \) denotes the distance from a point to a set. Thus \( d(x, H) = \inf \{ d(x, h(A)) \mid h \in \mathcal{N} \} \). The definition of \( V_c \) resembles the construction of a fundamental domain for a transformation group, where the neighbor maps play the part of the transformations.

Theorem 1. If OSC holds, the central open set \( V_c \) is a feasible open set. If OSC does not hold, then \( V_c \) is empty.

Proof. We show that \( V_c \) fulfills condition (1) whenever it is nonempty. It follows that if OSC does not hold \( V_c \) must be empty. To verify \( f_i(V_c) \subseteq V_c \), consider a point \( x \in V_c \) and \( y = f_i(x) \). Since \( f_i \) is a similarity map with factor \( r_i \),

\[
d(y, A) \leq d(y, f_i(A)) = r_i \cdot d(x, A) < r_i \cdot d(x, H) = d(y, f_i(H)) \leq d(y, H).
\]

In the last step, we used \( H \subseteq f_i(H) \) which follows from the fact that each \( f_i^{-1}f_j(a) \) can be written as \( f_i(f_j^{-1}f_i^{-1}f_j(a)) \).

Next, let \( i \neq j \) and \( x \in V_c \). Then \( d(x, A) < d(x, f_i^{-1}f_j(A)) \) by definition of \( V_c \).

Applying \( f_i \) on both sides of the inequality and dividing by \( r_i \), we obtain

\[
d(f_i(x), f_i(A)) < d(f_i(x), f_j(A)).
\]

The points of \( f_i(V_c) \) are nearer to \( A \) than to any other piece of \( A \). A similar statement holds for the points of \( f_j(V_c) \). This proves \( f_i(V_c) \cap f_j(V_c) = \emptyset \).

If OSC holds, then by Schief [6] there is an open set \( V \) with \( A \cap V \neq \emptyset \). Since \( V \) does not intersect \( \overline{H} \) (cf. Proposition 3), each point in \( V \cap A \) belongs to \( V_c \) and so \( V_c \) is nonempty.

Corollary 2. OSC holds if and only if \( A \) is not contained in \( \overline{H} \).

M. Moran [4] even claimed that OSC holds if and only if \( H \) contains no dense subset of \( A \), that is, \( A \neq \overline{A \cap H} \). But since his proof contains a gap, his assertion remains open as long as we do not know more about \( H \). So let us study the structure of forbidden points of \( A \) in greater detail.

3. The fixed points of neighbor maps

Hutchinson [3] characterized the self-similar set \( A \) as the closure of the set of fixed points of the \( f_i, i \in S^* \). It turns out that the set of forbidden points has a similar structure. Let \( J \) denote the set of fixed points of neighbor maps,

\[
J = \{ x \in \mathbb{R}^n \mid h(x) = x \text{ for some } h \in \mathcal{N} \}.
\]

Proposition 3. All points of the closure \( \overline{J} \) are forbidden points for \( A \), and \( H \subseteq \overline{J} \).
Assume $x \in J$ belongs to an open set $V$. Then $V$ contains the fixed point $y$ of a neighbor map $f_i^{-1} f_j$. Thus $f_i(V) \cap f_j(V)$ contains $f_i(y)$, so $V$ is not feasible.

To show that $J \subseteq J$ we fix a point $b \in H$, say $b \in f_i^{-1} f_j(A)$. We assume that $|i| < |j|$ and so that $h = f_i^{-1} f_j$ is contractive. Actually we may enlarge $j$ as far as we want, for the only requirement is that $f_i(b) \in f_j(A)$.

Let $c$ be the fixed point of the map $h = f_i^{-1} f_j$. For $a = h^{-1}(b)$ we have

$$|c - b| = |h(c) - h(a)| = r_h \cdot |c - a|.$$  

We fix $i$ and extend $j$ to obtain a sequence of $h_n$ such that $b \in h_n(A)$. In this procedure, one can show that $c$ is bounded, $r_h$ tends to 0, and $a$ is bounded since it is in $A$. Therefore, the fixed points of $h_n$ tend to $b$.

Our problem here is whether there are forbidden points outside $J$. For self-similar sets on the line, we will prove that there are no such points. When OSC holds, our statement is a bit more general. We start with a simple observation.

**Lemma 4.** (cf. [1], Prop. 1(i)) Given a forbidden point $x$ of $A$ and an $\varepsilon > 0$, there is a neighbor map $h$ with $|h(x) - x| < \varepsilon$.

**Proof.** Let $B$ denote the open ball with center $x$ and radius $\varepsilon/2$, and consider $V = \bigcup_{i \in S} f_i(B)$. Since $V$ is not a feasible open set, $f_i(V) \cap f_j(V) \neq \emptyset$ for some $i \neq j$. So there are $i, j \in S^n$ with $f_i f_j(B) \cap f_j f_i(B) \neq \emptyset$. The map $h = f_i^{-1} f_j$ fulfills the condition if $h$ is contractive; otherwise $h^{-1}$ fulfills the condition.

**Theorem 5.** Let the mappings $f_i(x) = u_i x + v_i$ on $\mathbb{C}^n$ with $u_i \in \mathbb{C}$ and $v_i \in \mathbb{C}^n$ satisfy OSC. Then any forbidden point belongs to $J$.

**Proof.** Any neighbor map can be written as

$$h(x) = rx + (1 - r) c \text{ or } h(x) = x + b \text{ with } r \in \mathbb{C} \text{ and } c, b \in \mathbb{C}^n.$$  

Let $x$ be a forbidden point. OSC means $\|h - id\| > \kappa$ for all neighbor maps and some $\kappa > 0$. Let $\varepsilon < \kappa/2$ be given and take $h$ from Lemma 4. $h$ cannot be a translation since then $\|h - id\| = |h(x) - x|$. Thus

$$\varepsilon > |h(x) - x| = |1 - r| \cdot |c - x|.$$  

By the definition of norm, there is a $y$ with $|y| \leq 1$ such that

$$\kappa \leq |h(y) - y| = |1 - r| \cdot |c - y|.$$  

Subtracting the two inequalities and dividing by $|1 - r|$, we obtain

$$(\kappa - \varepsilon)/|1 - r| < |c - y| \cdot |c - x| \leq |x - y| \leq |x| + 1.$$  

Now we use the first inequality again:

$$|c - x| < \frac{\varepsilon}{|1 - r|} < \frac{\varepsilon}{\kappa - \varepsilon} \cdot (|x| + 1) < \frac{2\varepsilon}{\kappa} \cdot (|x| + 1).$$

For $\varepsilon \to 0$ this shows that $x$ is in $J$.

**Theorem 6.** An IFS on $\mathbb{R}$ does not satisfy OSC if and only if $J = \mathbb{R}$.
We need only show that no OSC implies that \( J = \mathbb{R} \). Let \( f_i(x) = r_i x + d_i, \) \( 1 \leq i \leq m \). Without loss of generality, we may assume that \( d_1 = 0 \). It follows that \( 0 \in A \). Define \( D = \{ h(0) \mid h \in \mathcal{N} \} \).

First \( D \subseteq J \), for \( h(0) \in h(A) \subset J \) by Proposition 3. In the following, we will show that \( D = \mathbb{R} \) and hence \( J = \mathbb{R} \).

We can assume that \( r_1 > 0 \). Otherwise we consider the IFS formed by the \( f_{ij} \) with \( i,j \in S \) for which \( J \) is not larger and \( f_{11}(x) = r_1^2 x \).

Take any neighbor map \( h = f_1^{-1} f_j(x) \) where \( f_1^{-1}(x) = a_1 x + b_1 \) and \( f_j(x) = a_2 x + b_2 \). Then \( h(x) = a_1 a_2 x + a_1 b_2 + b_1 \). Pick any \( \delta > 0 \), we will show that there exist a neighbor map \( h^* \in \mathcal{N} \) such that

\[
\delta/2 \leq h^*(0) - h(0) \leq (1/r_1 + 1/2)\delta.
\]

Let \( g(x) = ax + b \) be a neighbor map in \( \mathcal{N} \). Denote \( g^{-1}(x) = x/a - b/a = a'x + b' \). Since there is no OSC, we can choose \( g \) arbitrarily near to the identity map. Without loss of generality, we may assume that \( a_1 b > 0 \); otherwise we exchange \( g \) and \( g^{-1} \).

We choose \( g \) so near to the identity map that

\[
|a - 1| a_1 b_2 < \delta/2, \quad |a_1 b| < \delta \quad \text{and} \quad \delta' < \delta/2, \quad |a_1 b'| < \delta.
\]

Let \( g_1(x) = (f_1^{-1})^k \cdot g \cdot f_j^k(x) \), then \( g_1(x) \in \mathcal{N} \) and \( g_1(x) = ax + r_1^{-k}b \). Choose the integer \( k \) such that

\[
\delta \leq r_1^{-k} a_1 b < \delta/r_1.
\]

Let \( h^*(x) = f_1^{-1} \cdot g_1 \cdot f_j(x) \). Then

\[
\delta/2 < h^*(0) - h(0) = (a - 1) a_1 b_2 + r_1^{-k} a_1 b < (1/r_1 + 1/2)\delta.
\]

Likewise let \( g_2(x) = (f_1^{-1})^k \cdot g^{-1} \cdot f_j(x) \), where \( k \) is chosen such that \( \delta \leq -r_1^{-k} a_1 b' < \delta/r_1 \). We get a map \( h_*(x) = f_1^{-1} \cdot g_2 \cdot f_j(x) \in \mathcal{N} \) such that

\[
\delta/2 < h_*(0) - h_*(0) \leq (1/r_1 + 1/2)\delta.
\]

Hence for any \( \delta > 0 \), and any \( x \in D \), there are two points \( y_1, y_2 \in D \) such that

\[
\delta/2 \leq y_1 - x \leq (1/r_1 + 1/2)\delta, \quad \delta/2 \leq x - y_2 \leq (1/r_1 + 1/2)\delta.
\]

Therefore \( D = \mathbb{R} \). \( \square \)

References


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